

System modeling and simulation(ME340)

Chapter 9. Transient response and block diagram model

9.6 Modeling system with block diagrams

邹渊

Yuan Zou

Tel: 68944115

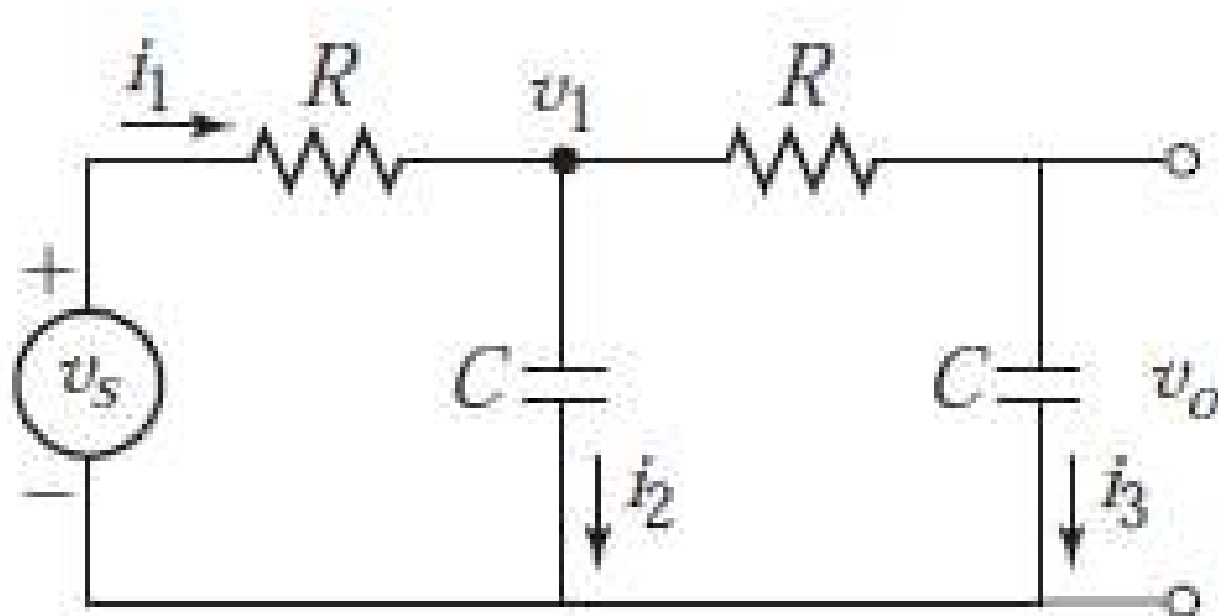
[Email: zouyuan@bit.edu.cn](mailto:zouyuan@bit.edu.cn)

Visual expression of dynamics

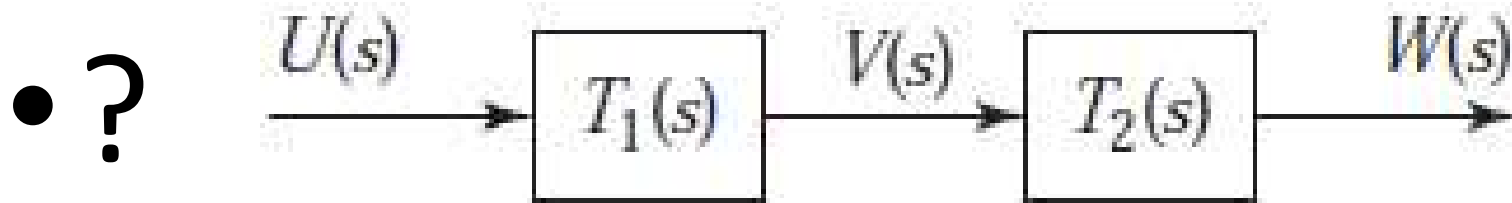
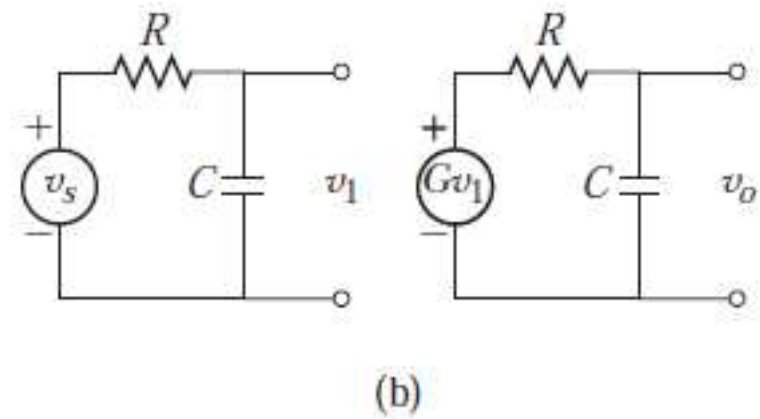
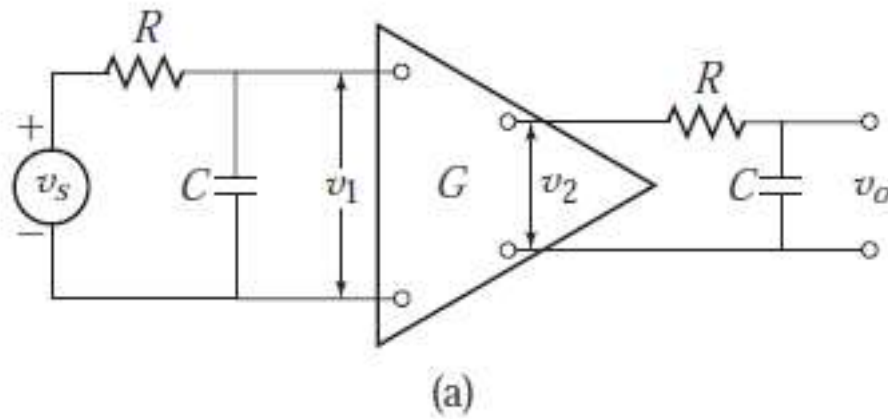
- Block diagram make it possible.
- Algebraic representation of the system equations in terms of transfer function
- Easier manipulation for analysis and desing
- Graphical representation is good for communication and understanding.

RC loops: coupled

- Draw block diagram for the circuit



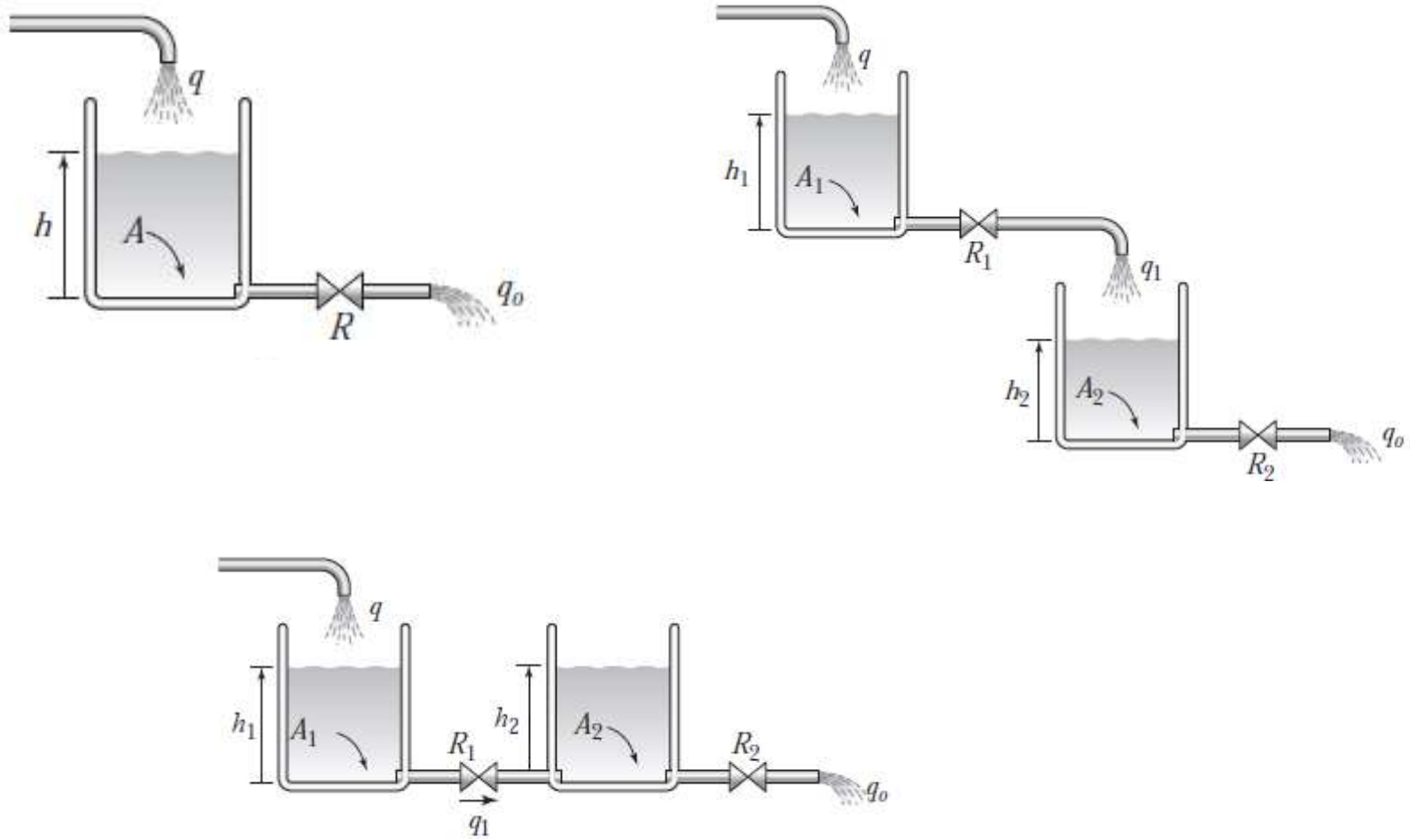
RC loops: uncoupled



Armature-controlled motor

Field-controlled motor

Liquid-level system



System modeling and simulation(ME340)

Chapter 9. Transient response and block diagram model

9.6 Matlab application

邹渊

Yuan Zou

Tel: 68944115

[Email: zouyuan@bit.edu.cn](mailto:zouyuan@bit.edu.cn)

Computing response characteristic with matlab

- `Step(sys)`
- `Impulse(sys)`

Block diagram algebra using matlab

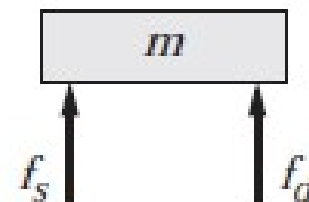
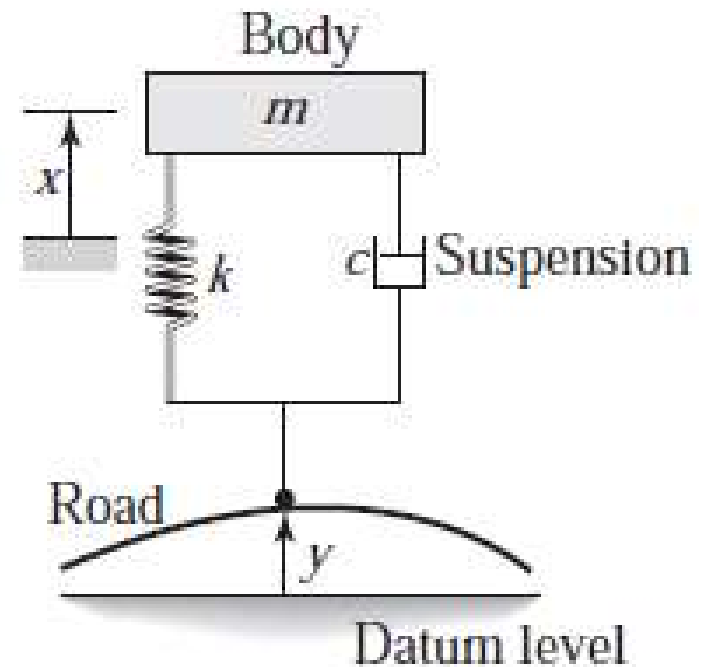
- `Series(sys1,sys2)`
- `Feedback(sys1,sys2)`

Simulink applications

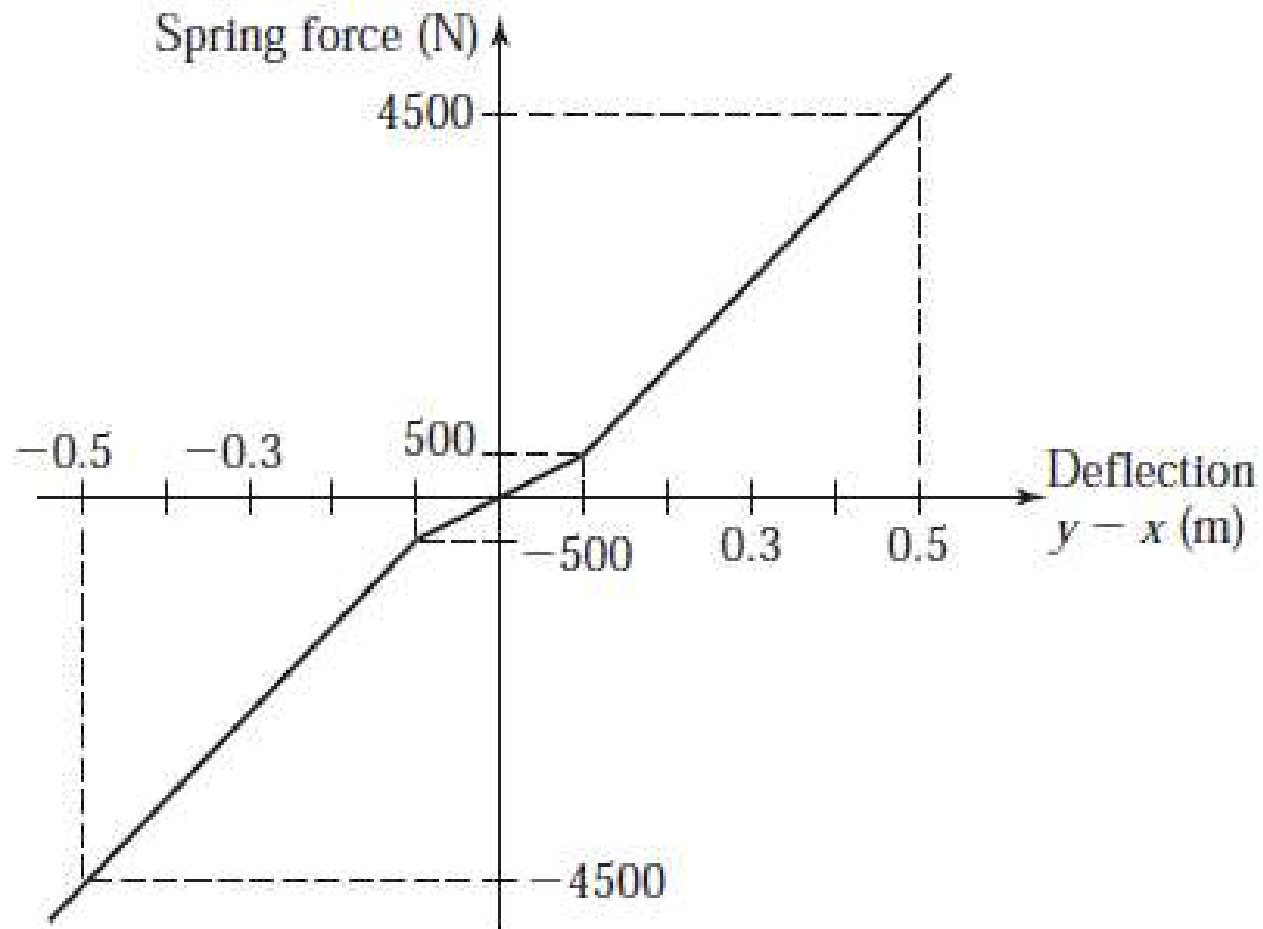
- Linear and linearized model are useful for predicting the behavior of dynamic systems.
WHY
- But input is not always step, impulse or periodical signals. Normally we want to test more.
- Simulink is good at for that. Most import: it is block diagram-based.

Hands-on exercise: vehicle suspension response

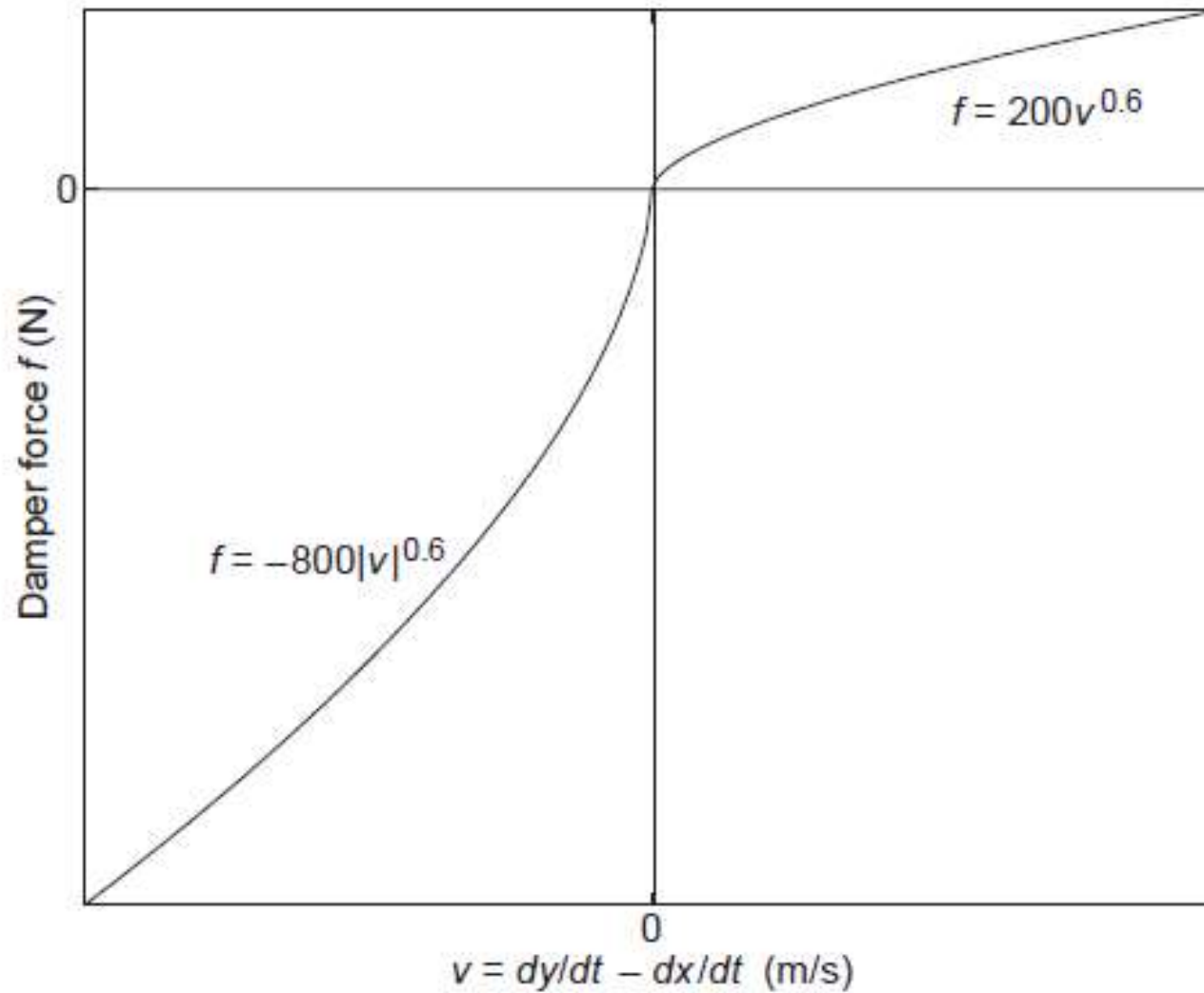
- $m=400\text{kg}$
- k and c is nonlinear
- Bump is trapezoidal function



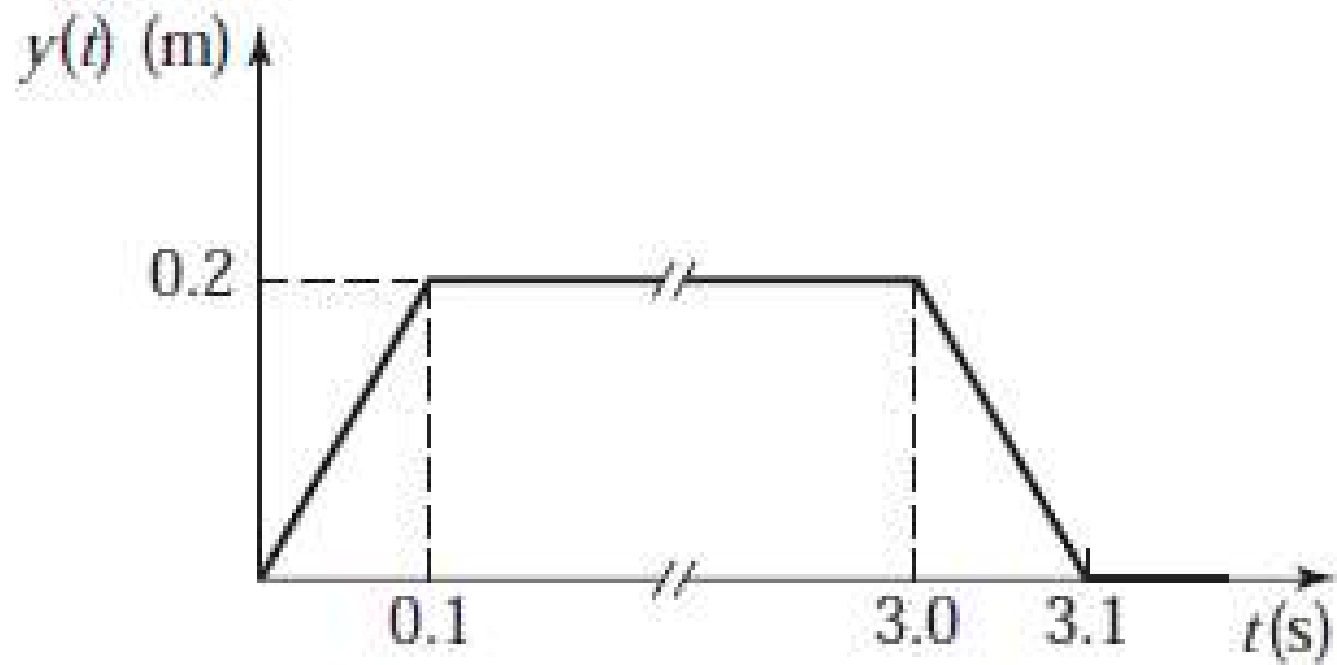
Spring characteristic



Damping characteristic



Bump profile



Hands-on

- Dynamic equations
 - Block diagram
 - Simulink modeling
-
- HW: 9.7,9.13,9.27,9.31,9.33,9.48,9.51,9.57

What we learned.

- Chapter 1
- Chapter 3
- Chapter 4 + 9 HW + 2 LAB
- Chapter 5
- Chapter 6
- Chapter 8
- Chapter 9